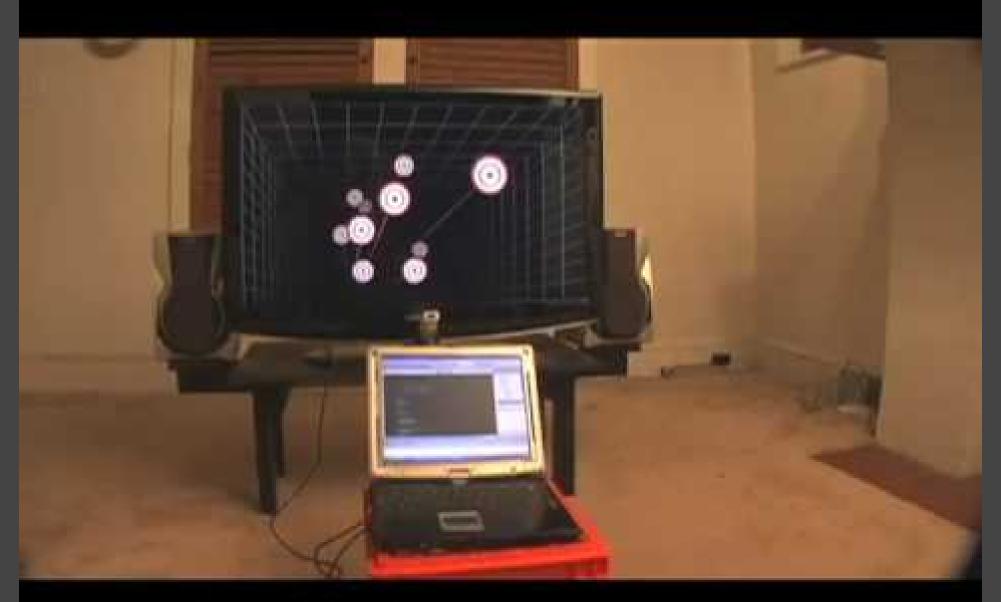
KINECT

Hardware hacking







VR Display (with head tracking)

Hardware hacking

Open Kinect

<u>The Open Kinect project – THE OK PRIZE – get \$2,000</u> <u>bounty for Kinect for Xbox 360 open source drivers</u>



Update: We've increased it to \$3,000 – why? We just read this at CNET...

But Microsoft isn't taking kindly to the bounty offer. Bounty offered for open-source Kinect driver - "Microsoft does not condone the modification of its products," a company spokesperson told CNET. "With Kinect, Microsoft built in numerous hardware and software safeguards designed to reduce the chances of product tampering. Microsoft will continue to make advances in these types of safeguards and work closely with law enforcement and product safety groups to keep Kinect tamper-resistant."

4 Novembre Get \$2,000 bounty for Kinect for Xbox 360 open source drivers

10 Novembre WE HAVE A WINNER – Open Kinect driver (s) released



http://openkinect.org

Microsoft

The first thing to talk about is, Kinect was not actually hacked. Hacking would mean that someone got to our algorithms that sit inside of the Xbox and was able to actually use them, which hasn't happened. Or, it means that you put a device between the sensor and the Xbox for means of cheating, which also has not happened. That's what we call hacking, and that's what we have put a ton of work and effort to make sure doesn't actually occur. What has happened is someone wrote an open-source driver for PCs that essentially opens the USB connection, which we didn't protect, by design, and reads the inputs from the sensor. The sensor, again, as I talked earlier, has eyes and ears, and that's a whole bunch of noise that someone needs to take and turn into signal.

Mr. ALEX KIPMAN (Director of Incubation for Xbox at Microsoft)

Two other libraries

http://www.openni.org/

- by the makers of the Kinect sensor
- supports skeleton detection

http://codelaboratories.com/nui

- Windows
- not very developed, but...
- works (partly) with Processing & OpenFrameworks

Hardware hacking

How-to

Let's first check the connected USB devices with

system_profiler SPUSBDataType

http://ladyada.net/learn/diykinect/

Kinect

Inputs / Outputs

Kinect

- RGB video
- IR video
- raw distance (11bit = 2048 values)
 - distance as a grayscale picture (8bit = 256 values)

640x480 @ 30fps

- 2 accelerometers
- multi-array microphone (not supported yet)
- controllable motor

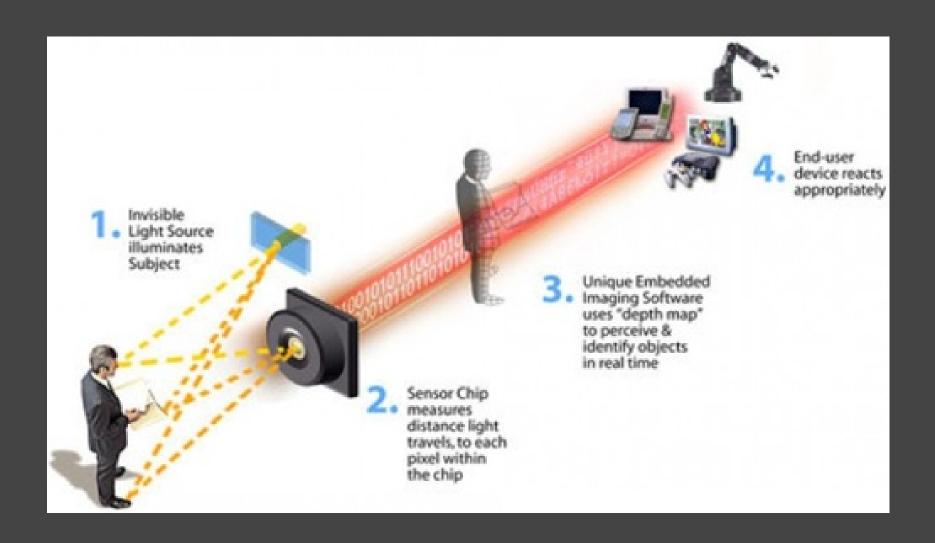
Kinect: area

- sensor has a field of view of 57° x 43°
- can detect distances between 80cm 6m
- practically, the Xbox soft uses a range of 1.2 3.5m
- at the minimum distance of 80cm the resolution is +/- 1.3mm per pixel
- but there's noise!

How

can the Kinect see in 3D?

Time-of-flight camera?



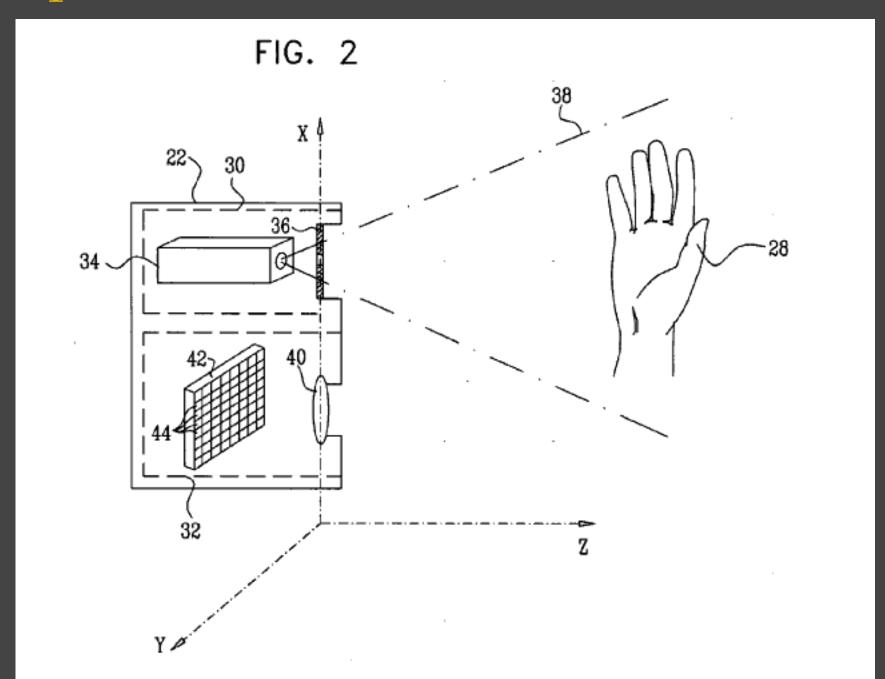
Time-of-flight camera?

- needs a modulated laser
- and a camera that can mesure that "time-of-flight"

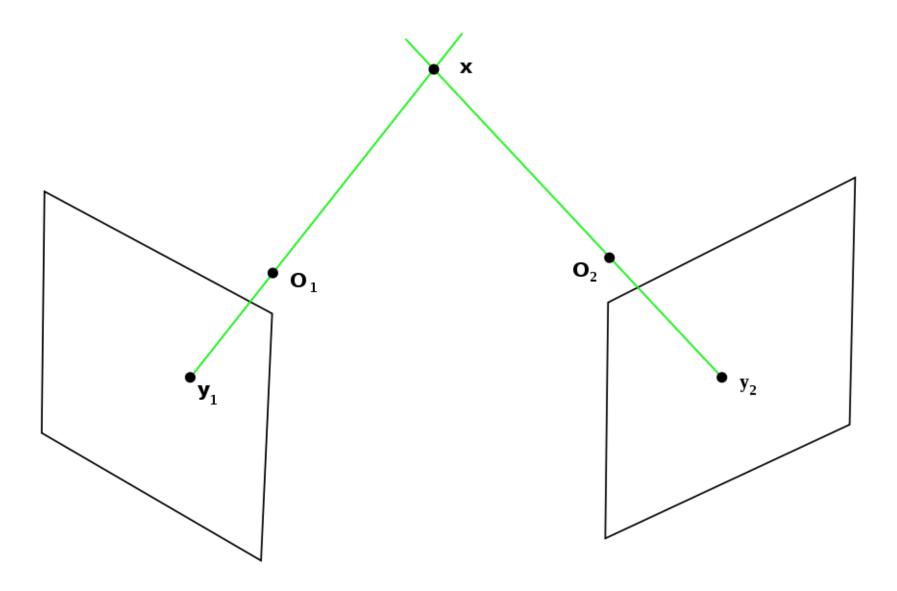
According to PrimeSense

"PrimeSense's technology for acquiring the depth image is based on Light Coding™. Light Coding works by coding the scene volume with near-IR light. The IR Light Coding is invisible to the human eye. The solution then utilizes a standard off-the-shelf CMOS image sensor to read the coded light back from the scene. PrimeSense's SoC chip is connected to the CMOS image sensor, and executes a sophisticated parallel computational algorithm to decipher the received light coding and produce a depth image of the scene. The solution is immune to ambient light, and works in any indoor environment."

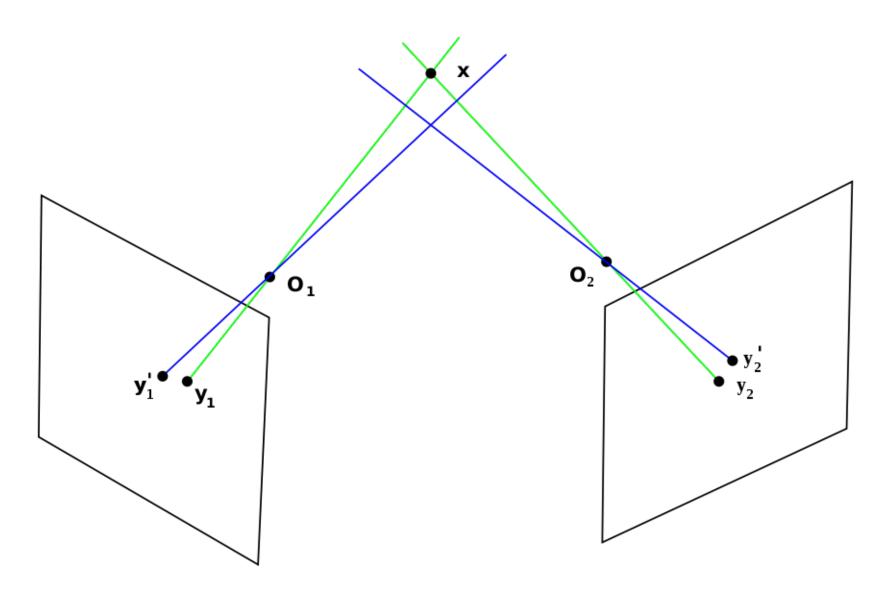
The patent (click)

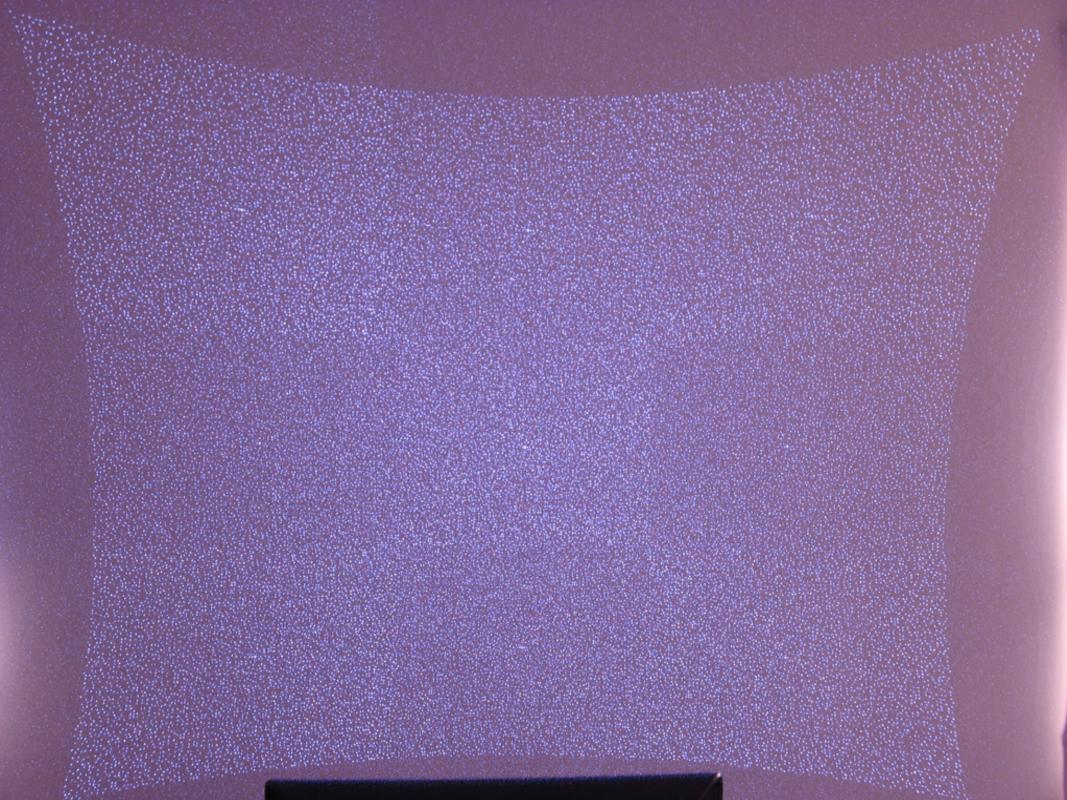


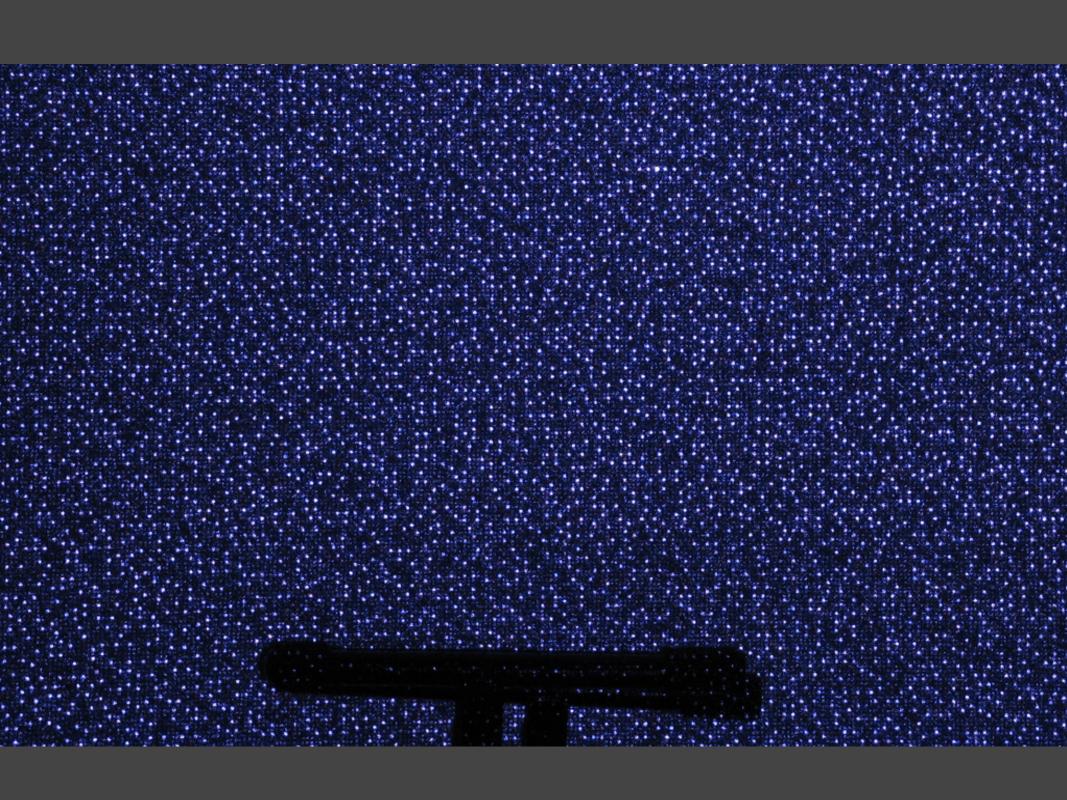
Stereo triangulation

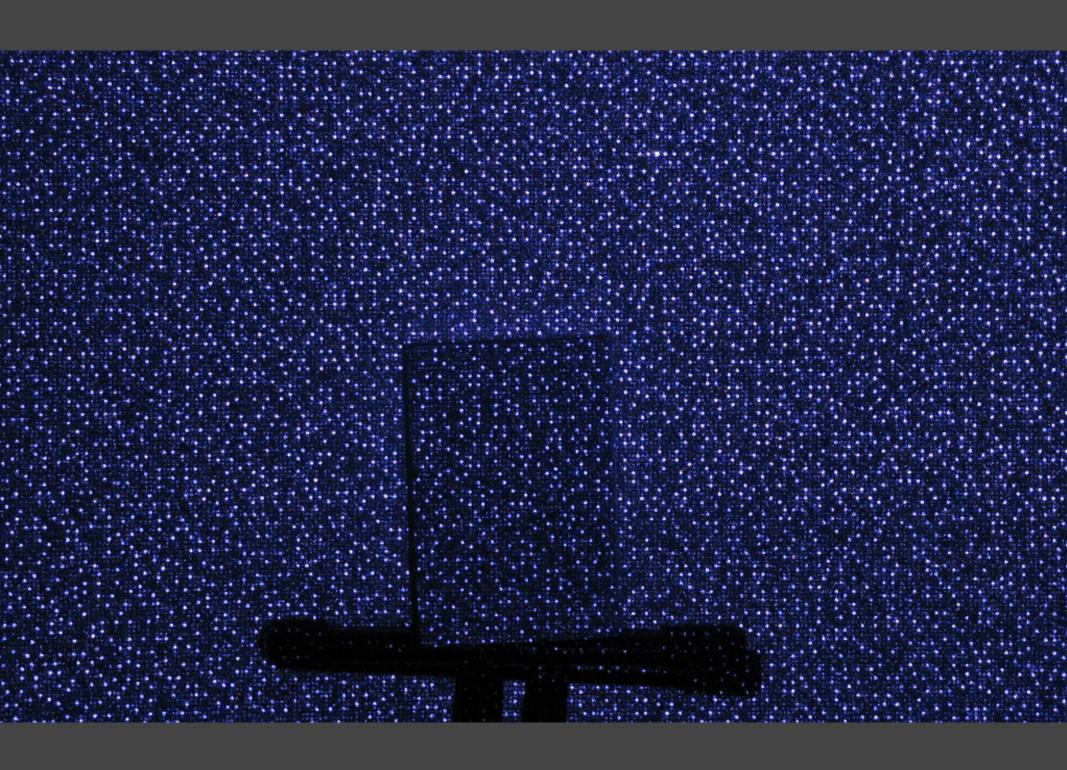


Stereo triangulation











Similar to Structured Light



How Kinect helps us

with computer vision



Demos

- CV
- 3D
- Skeleton
- Multitouch

Libraries / Tools

Google Doc

- OS X : OpenFrameworks / Processing?
 - -> Libfreenect (OpenKinect)
- Windows?
 - -> CL NUI :(
- Skeleton?
 - OSCeleton for everyone